Speech recognition and synthesis

More about ASR

- Introduction
- Dynamic programming
- Viterbi algorithm
- Other approaches to decoding
- Training acoustic models
- FLOSS resources
- Assignment
- Bibliography

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Introduction

Two technologies are needed to make the HMM framework practical

 Decoder technology to find the argmax P(Observation|Words) · P(Words) Words

Many pictures (and their copyrights) are from [Jurafsky and Martin(2000)]



Introduction

Two technologies are needed to make the HMM framework practical

- Decoder technology to find the argmax P(Observation|Words) · P(Words) Words
- Determining the stochastic parameters of the HMM state automaton, i.e. training

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Look for best alignment: Minimum edit distance

- Delete
- Insert
- Substitute

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\begin{aligned} & \mathsf{function} \; \mathsf{MIN-EDIT-DISTANCE}(target, source) \; \mathsf{returns} \; min-distance \\ & n \leftarrow \mathsf{LENGTH}(target) \\ & m \leftarrow \mathsf{LENGTH}(source) \\ & \mathsf{Create} \; a \; \text{distance} \; \mathsf{matrix} \; distance[n+1,m+1] \\ & distance[0,0] \leftarrow 0 \\ & \mathsf{for} \; \mathsf{each} \; \mathsf{cow} \; j \; \mathsf{from} \; 0 \; \mathsf{to} \; n \; \mathsf{do} \\ & \mathsf{for} \; \mathsf{each} \; \mathsf{cow} \; j \; \mathsf{from} \; 0 \; \mathsf{to} \; n \; \mathsf{do} \\ & \mathsf{for} \; \mathsf{each} \; \mathsf{row} \; j \; \mathsf{from} \; 0 \; \mathsf{to} \; n \; \mathsf{do} \\ & \mathsf{for} \; \mathsf{each} \; \mathsf{row} \; j \; \mathsf{from} \; 0 \; \mathsf{to} \; n \; \mathsf{do} \\ & \mathsf{distance}[i, j] \leftarrow \mathsf{MIN}(distance[i-1, j] + \mathit{ins-cost}(target_i), \\ & distance[i-1, j-1] + subst-cost(source_j, \mathsf{target}_i), \\ & distance[i, j-1] + del-cost(source_j)) \end{aligned}
```

Fill a matrix with cumulative edit distances, distance[i, j] = min of distance[i - 1, j] + insert-cost(target_i) distance[i - 1, j - 1] + substitution-cost(source_j, target_i) distance[i, j - 1] + deletion-cost(source_j)

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 \begin{array}{l} \textbf{function MIN-EDIT-DISTANCE}(target, source) \ \textbf{returns } min-distance \\ n \leftarrow \text{LENGTH}(target) \\ m \leftarrow \text{LENGTH}(source) \\ \text{Create a distance matrix } distance[n+1,m+1] \\ distance[0,0] \leftarrow 0 \\ \textbf{for each column } i \ \textbf{from 0 to n do} \\ \textbf{for each row } j \ \textbf{from 0 to n do} \\ distance[i,j] \leftarrow \text{MIN}(distance[i-1,j] + ins-cost(target_i), \\ distance[i,j-1] + subst-cost(source_j, \text{target}_i), \\ distance[i,j-1] + del-cost(source_j)) \end{array}
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n	9	10	11	10	11	12	11	10	9	8
0	8	9	10	9	10	11	10	9	8	9
i	7	8	9	8	9	10	9	8	9	10
t	6	7	8	7	8	9	8	9	10	11
n	5	6	7	6	7	8	9	10	11	12
e	4	5	6	5	6	7	8	9	10	11
t	3	4	5	6	7	8	9	10	11	12
n	2	3	4	5	6	7	8	8	10	11
i	1	2	3	4	5	6	7	8	9	10
#	0	1	2	3	4	5	6	7	8	9
	#	e	х	e	с	u	t	i	0	n

Trace back the choices of the minimal distance (bold numbers)

- This finds the globally minimal cost path
- Full search unwieldy for large and complex matrices
- In general, searches are pruned to exclude paths that deviate far from the diagonal: Beam search

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• Each word is modeled as a Finite State Machine

- Individual phoneme HMMs are trained from a corpus that does not contain all the words
- A pronunciation dictionary contains all word models
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Viterbi algorithm result *"for I need a"* [Jurafsky and Martin(2000)]

• Whole sequence on X axis

- All word models on the other axis
- Switch to (any) new word after reaching the end of the current word
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I the	0.00018	need the	0.012	# The	0.016
I on	0.000047	need on	0.000047	# On	0.00077
ΙI	0.039	need I	0.000016	# I	0.079
the need	0.00051	on need	0.000055		
the the	0.0099	on the	0.094		
the on	0.00022	on on	0.0031		
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Bigram probabilities [Jurafsky and Martin(2000)]

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Single pronunciation automaton for I, need, on, and the [Jurafsky and Martin(2000)]

- Bigram probabilities connect the word models
- Merge start and end states of connected words
- Need for *pruning* is apparent

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Viterbi algorithm



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function VITERBI(observations of len T, state-graph) returns best-path
  num-states \leftarrow NUM-OF-STATES(state-graph)
  Create a path probability matrix viterbi[num-states+2,T+2]
  viterbi[0.01 \leftarrow 1.0
  for each time step t from 0 to T do
     for each state s from 0 to num-states do
        for each transition s' from s specified by state-graph
           new-score \leftarrow viterbi[s, t] * a[s,s'] * b_{s'}(o_t)
           if ((viterbi[s', t+1] = 0) || (new-score > viterbi[s', t+1]))
              then
                     viterbi[s', t+1] \leftarrow new-score
                     back-pointer[s', t+1] \leftarrow s
  Backtrace from highest probability state in the final column of viterbi[] and
return path
```

Extended version of the edit distance [Jurafsky and Martin(2000)]

- $a[s, s'] = P(s \rightarrow s')$
- $b_{s'}(o_t) = P(o_t|s')$

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Individual state columns in Viterbi algorithm [Jurafsky and Martin(2000)]

- The actual entries for the Automaton
- Note the problems for a 20,000 word dictionary

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Use structured, context sensitive phone units

- Single phone units perform bad due to coarticulation
- Begin differs from End (eg, /d/)
- 60 context dependent triphones \Rightarrow 60³ = 216000 models
- Cluster contexts, eg, on manner and place of articulation

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Other approaches to decoding: Introduction

The standard HMM model has limitations

- Viterbi decoder penalizes multiple pronunciations
- Viterbi decoder does not work for anything more complex than bigram
- It is not possible to include other linguistic knowledge



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 - Intonation
 - Semantics
 - Speaker identification
 - Expressive speech tags
 - Task related knowledge



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- Keep N-best utterance list or word lattice
- Rescore the probabilities with the extra knowledge
 - A trigram or higher grammar
 - Phoneme duration probability Chapt 7 [Wang(1997)]
 - Parallel Intonation and Accent detector (HMM) example without N-best [Taylor et al. (1998) Taylor, King, Isard, and Wright]
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Two stage N-best decoding [Jurafsky and Martin(2000)]

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- Viterbi uses best path upto position t to get to t+1
- A* uses complete forward algorithm (exact likelihoods)
- A* searches potential utterances best-first



Stack, or A^{*}, decoding [Jurafsky and Martin(2000)]

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function STACK-DECODING() returns min-distanceInitialize the priority queue with a null sentence.Pop the best (highest score) sentence s off the queue.If (s is marked end-of-sentence (EOS)) output s and terminate.Get list of candidate next words by doing fast matches.For each candidate next word w:Create a new candidate sentence s + w.Use forward algorithm to compute acoustic likelihood L of s + wCompute language model probability P of extended sentence s + w.Compute "score" for s + w (a function of L, P, and ???)if (end-of-sentence) set EOS flag for s + w.Insert s + w into the queue together with its score and EOS flag

Stack decoding [Jurafsky and Martin(2000)]

- At each point, the A^* looks for the most likely next word
- Acoustic likelihood is part of the criterium
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If music be the food of love [Jurafsky and Martin(2000)] • "Start Alice" has highest score: 40 • "Start if" has highest score: 30 • "Start if music" has highest score: 32

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- Use fast match heuristics for selecting next words
- Longer utterances have lower probabilities, score should correct for this
- A^* evaluation function: $f^*(p) = g(p) + h^*(p)$
- g(partial path) = P(O|Words) · P(Words), i.e. the likelihood until now
- h*(p) something that correlates with number of words in the rest of the utterance
- Defining a good $h^*(p)$ is an interesting (unsolved) problem

- Use fast match heuristics for selecting next words
- Longer utterances have lower probabilities, score should correct for this
- A^* evaluation function: $f^*(p) = g(p) + h^*(p)$
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Other approaches to decoding: A^* fast match



A tree structured lexicon from SPHINX [Gouvêa()][Jurafsky and Martin(2000)]

- Need to get forward probabilities of potential continuations fast
- Tree lexicon shares forward probabilities between words
- Allows early pruning of search trees

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Training acoustic models: Introduction

Determine P(Observation|Words), i.e. the transition probability between phone states a_{ij} and the acoustic likelihood of the speech vectors $b_j(o_k)$

- Large, "transcribed" speech corpus (on text level)
- Coverage of speakers and language types
- Recorded under the same conditions as intended use, eg, over the phone or in a driving car
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van Son & Weenink (IFA, ACLC)

Speech recognition and synthesis

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If all states were known [Jurafsky and Martin(2000)]

•
$$a_{ij} = \frac{\#S_{ij}}{\#S_{i*}}$$
 (count transitions and states
• $b_i(O_k) = \frac{\#(O_k \& S_i)}{\#S_i}$ (for discrete O_k)

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1



If observations are continuous vectors $_{\mbox{\scriptsize [SPH()]}}$

•
$$b_i(O_t) \Rightarrow N\{\hat{\mu_i}, \hat{\Sigma_i}\}$$

$$\hat{\mu}_i = \frac{1}{T_i} \sum_{t=1}^{T_i} O_t$$

•
$$\hat{\Sigma}_i = \frac{1}{T_i} \sum_{t=1}^{T_i} [(O_t - \hat{\mu}_i)'(O_t - \hat{\mu}_i)]$$



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States have to be estimated. Use an iterative procedure $_{App\ D}$ $_{[Jurafsky\ and\ Martin(2000)]}$

• Run the recognizer on the corpus with the known words



• Update all values and start again

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States have to be estimated. Use an iterative procedure $_{App\ D}$ $_{[Jurafsky\ and\ Martin(2000)]}$

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Calculate â_{ij} = expected #S_i→S_j/expected #S_i→S_{*}
Calculate b_j(v_k) = expected #S_j observing v_k/expected #S_j
Update all values and start again

-

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States have to be estimated. Use an iterative procedure $_{App\ D}$ $_{[Jurafsky\ and\ Martin(2000)]}$

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States have to be estimated. Use an iterative procedure $_{\mbox{App D}}$ $_{\mbox{[Jurafsky and Martin(2000)]}}$

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• Calculate
$$\hat{a}_{ij} = \frac{expected \ \#S_i \rightarrow S_j}{expected \ \#S_i \rightarrow S_*}$$

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Image: A matrix

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Appendix A



van Son & Weenink (IFA, ACLC)

Speech recognition and synthesis

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Image: A matrix



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Image: A matrix

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